

Theorem provers within theorem provers

Experiments with modal logic in HOL Light [★]

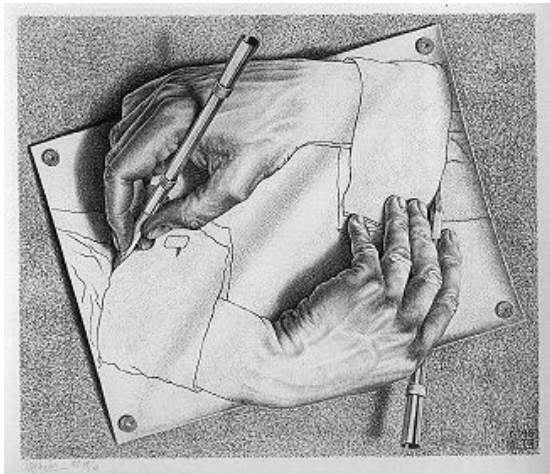
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[★] Based on joint work with Marco Maggesi and Rocco De Nicola
within the project “IT Matters: Methods and Tools for Trustworthy Smart Systems” (PRIN 2017FTXR7S)

Interactions of Proof Assistants and Mathematics
Regensburg, 18–29. Sept. 2023

Drawing Hands



Picture credit: "The Magic of M.C. Escher", WikiMedia

Quis demonstrat ipsos demonstratores?

- ▶ Mathematical proofs are the most reliable form of verification.
 - ▶ By computerising mathematics through deductive systems, we obtain a highest certificate of correctness.
 - ▶ But deductive systems are themselves study object of mathematics.
- ∴ Deductive systems could be formalised in proof assistants too.

Our goal

Current

- Use HOL Light
 - as main environment to **formalise** results/theorems about syntax and semantics of (normal) modal logics.
 - to **make precise** the internalisation of semantics in the syntax of (many) contemporary proof systems for modal logics.
 - to **mechanise proof search** in (the formalised version of) those proof systems by defining new specific tactics reflecting the rules of the proof system under investigation.
- As by-product, obtain a **decision procedure** implemented in HOL Light for the modal logic under investigation, which works as a **countermodel constructor** to the input formula when needed.

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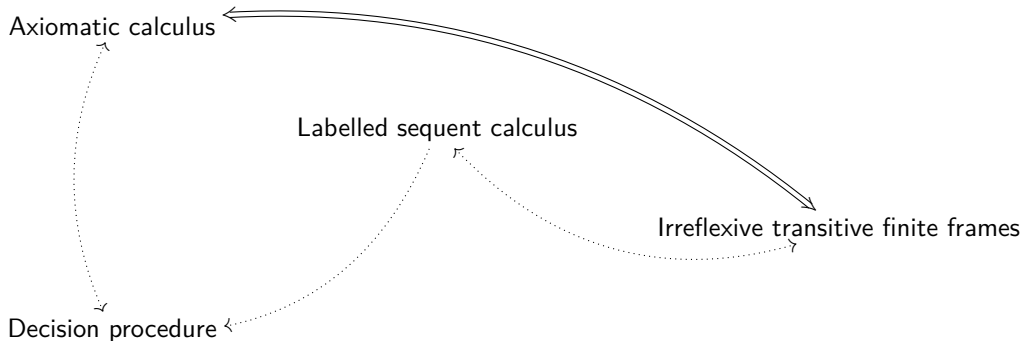
Long term

- ◇ Our methodology is not strictly related to a specific modal system, and we might apply it to logics relevant to e.g. system security and verification
⇒ “Proof-theoretic” alternatives to model checking, SATs, etc.
- ◇ Since it is based on a formal counterpart to internalisation in proof systems, theoretical advances in the latter can be rephrased in our setting, e.g. endowing possible worlds with “structure”
⇒ Mechanised deductive systems for compositional/parametric process analysis

This talk

The prototype

GL library



Code: <https://github.com/jrh13/hol-light/>, directory **GL**

Paper: *Mechanising Gödel-Löb provability logic in HOL Light*, J. Autom. Reasoning 67, 29

([Open Access](#))

Outline

Introduction

Formalization

- Syntax and semantics

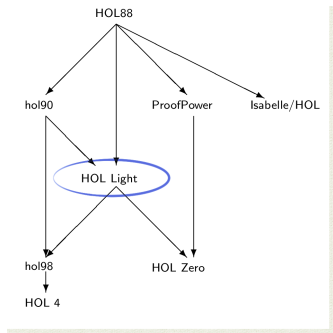
- Modal adequacy

- Internal theorem prover

Demo

Brief glance at HOL Light

(Harrison 2017)



- Clean logical foundations \approx *Principia Mathematica*
- LCF-style proof checker based on polymorphic simple type theory \approx small class of *primitive inference rules* for creating theorems + *derived inference rules* to be programmed on top
 - \Rightarrow 10 primitive rules
 - \Rightarrow 2 conservative extension principles
 - \Rightarrow Axioms of choice, extensionality, and infinity
- Written as an OCaml program \approx **three datatypes for the logic**: `hol_type`, `term`, and `thm`
- Goal-directed proof development \approx **tactic(al)s** + **automated methods** (in the appropriate domains)

Despite its simple foundations, HOL Light includes a large library of mathematical results in topology, analysis, Euclidean geometry, QBF, floating point algorithms, FOL, limitative results, ...

We consider a propositional modal language \mathcal{L}_\square whose formulas have one of the following forms:

$$p \mid \top \mid \perp \mid \neg A \mid A \wedge B \mid A \vee B \mid A \rightarrow B \mid A \leftrightarrow B \mid \square A.$$

GLaxiom, GLproves

GL denotes the axiomatic calculus made of:

- ▶ Axioms of CPC
- ▶ Axiom K : $\square(A \rightarrow B) \rightarrow \square A \rightarrow \square B$
- ▶ Axiom GL : $\square(\square A \rightarrow A) \rightarrow \square A$
- ▶ MP Rule $\frac{A \rightarrow B \quad A}{B}$
- ▶ Nec Rule $\frac{A}{\square A}$

Gödel-Löb Logic

Relational semantics

A **relational frame** is made of a set of “possible worlds” W , together with an accessibility relation $R \subseteq W \times W$.

For GL, we consider **irreflexive transitive finite frames (ITF)**:

- ▶ for no $x \in W$, xRx ;
- ▶ if xRy and yRz , then xRz ;
- ▶ W is a finite set.

By introducing a forcing relation $x \Vdash A$ between worlds and formulas, we get a **relational model** and a general notion of validity in a **class of models** (**holds**, **holds_in**, and **valid**).

Adequacy theorem

Soundness

Theorem (GL_ITF_VALID)

For any formula A , if $\text{GL} \vdash A$, then $\text{ITF} \models A$.

Corollary (GL_consistent)

Gödel-Löb logic is consistent.

Adequacy theorem

Completeness

Theorem (COMPLETENESS_THEOREM_GEN)

If $\text{GL} \not\models A$, then there exists an irreflexive transitive finite model \mathcal{M} such that $\mathcal{M} \not\models A$.

Proof.

We formalise (and adapt) the proof in (Boolos 1995), by working with finite *lists* of formulas.

This allows us to prove the theorem for models built on the type form `list` (COMPLETENESS_THEOREM), which is unpleasant from a computational view-point.

Therefore, we generalise the result by

- ▶ defining the notion of **bisimulation** between models (BISIMULATION),
- ▶ proving that **bisimilar structures satisfy the same formulas** (BISIMILAR_VALID),
- ▶ defining a bisimulation between the list-based countermodel and its analogous based on sets of formulas (GL_COUNTERMODEL_FINITE_SETS).

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Completeness, directly

The formalism of labelled sequent calculi allows the development of a direct proof of completeness of logical systems w.r.t. relational frames (Negri 2014).

In particular, proof-construction algorithms provide all the information needed for extracting a countermodel from a failed proof-search in a (labelled) sequent calculus (Troelstra and Schwichtenberg 2000).

$$\begin{array}{c}
\frac{}{x : p, \Gamma \Rightarrow \Delta, x : p} \textit{Init} \\
\frac{x : A, x : B, \Gamma \Rightarrow \Delta}{x : A \wedge B, \Gamma \Rightarrow \Delta} \mathcal{L}\wedge \\
\frac{x : A, \Gamma \Rightarrow \Delta \quad x : B, \Gamma \Rightarrow \Delta}{x : A \vee B, \Gamma \Rightarrow \Delta} \mathcal{L}\vee \\
\frac{\Gamma \Rightarrow \Delta, x : A}{x : \neg A, \Gamma \Rightarrow \Delta} \mathcal{L}\neg \\
\frac{\Gamma \Rightarrow \Delta, x : A \quad x : B, \Gamma \Rightarrow \Delta}{x : A \rightarrow B, \Gamma \Rightarrow \Delta} \mathcal{L}\rightarrow \\
\frac{y : A, xRy, x : \Box A, \Gamma \Rightarrow \Delta}{xRy, x : \Box A, \Gamma \Rightarrow \Delta} \mathcal{L}\Box \\
\frac{}{xRx, \Gamma \Rightarrow \Delta} \textit{Irref}
\end{array}
\qquad
\begin{array}{c}
\frac{}{x : \perp, \Gamma \Rightarrow \Delta} \mathcal{L}\perp \\
\frac{\Gamma \Rightarrow \Delta, x : A \quad \Gamma \Rightarrow \Delta, x : B}{\Gamma \Rightarrow \Delta, x : A \wedge B} \mathcal{R}\wedge \\
\frac{\Gamma \Rightarrow \Delta, x : A, x : B}{\Gamma \Rightarrow \Delta, x : A \vee B} \mathcal{R}\vee \\
\frac{x : A, \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta, x : \neg A} \mathcal{R}\neg \\
\frac{x : A, \Gamma \Rightarrow \Delta, x : B}{\Gamma \Rightarrow \Delta, x : A \rightarrow B} \mathcal{R}\rightarrow \\
\frac{xRy, y : \Box A, \Gamma \Rightarrow \Delta, y : A}{\Gamma \Rightarrow \Delta, x : \Box A} \mathcal{R}\Box \textit{L\"ob}_{(y!)} \\
\frac{xRz, xRy, yRz, \Gamma \Rightarrow \Delta}{xRy, yRz, \Gamma \Rightarrow \Delta} \textit{Trans}
\end{array}$$

Correspondences

Forcing

SEMANTIC NOTATION	$x \Vdash A$
LABELLED SEQUENT CALCULUS NOTATION	$x : A$
HOL LIGHT NOTATION	holds (W,R) $\forall A x$

How to employ these correspondences in our setting?

Shallow embedding

We adapt the goal stack mechanism of HOL Light to automate the proof development in G3KGL via new HOL Light tactics: when the very goal stack is dealing with

- ▶ forcing statement as goal
 \rightsquigarrow tactics mimicking \mathcal{R} -rules;
- ▶ forcing statement as hypothesis
 \rightsquigarrow tactics mimicking \mathcal{L} -rules.

Decision algorithm

To check whether a formula A is a theorem of GL, we programmed the tactic `GL_TAC` to perform a complete proof-search in G3KGL embedded in HOL Light.

From that tactic, we define the expected `GL_RULE` automating the whole process: given the formula A , the rule returns:

- a **new theorem in HOL Light**, stating that A is derivable in GL, whenever the proof-search positively terminates;
- a **countermodel** to A , that is extracted from the top-most sequent built during the automated proof-search.

Short Demo

Put in perspective

- Formalising meta-theoretical results about non-classical logics provides a basis for **implementing** *within* the theorem prover at hand **an automated theorem prover/decision procedure** for the logic under investigation
- **Internalisation methods** through labelling are a formalisation in disguise: such a correspondence is **made precise by using a proof assistant**
- **The prototype for GL can be extended and refined**; in particular, we would like to return a complete tree of labelled sequents whenever the automated proof-search positively terminates
- We have worked so far with labelled sequent calculi involving world labels, but if the structure of a label is defined by rules (**SOS?**) we can extend the embedding by extending the very sequent calculus
- Extending the theory would provide an **alternative tool for formal verification of processes** which differs from both model checking (no black boxes) and main-stream automated theorem provers implemented in Prolog

Many thanks for listening!

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Many thanks for listening!

References

- ▷ Boolos, G. (1995). *The logic of provability*. Cambridge University Press.
- ▷ Harrison, J. (2017). *The HOL Light Tutorial*.
- ▷ Maggesi, M., PB, C. (2023). *Mechanising Gödel-Löb provability logic in HOL Light*, J. Autom. Reasoning 67, 29.
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- ▷ Troelstra, A. S., Schwichtenberg, H. (2000). *Basic proof theory* (No. 43). Cambridge University Press.